

Unit - 3 Three Phase Circuits

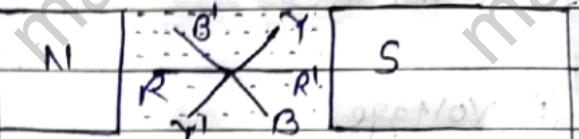
* Generation of 3 phase alternating EMF :

• Principle :

- The single phase supply is generated using a single turn alternator. Thus if armature consists of only one winding, then

only one Alternating voltage is produced.

- But if the armature winding is divided into three groups which are displaced by 120° from each other then it is possible to generate three alternating vfg.



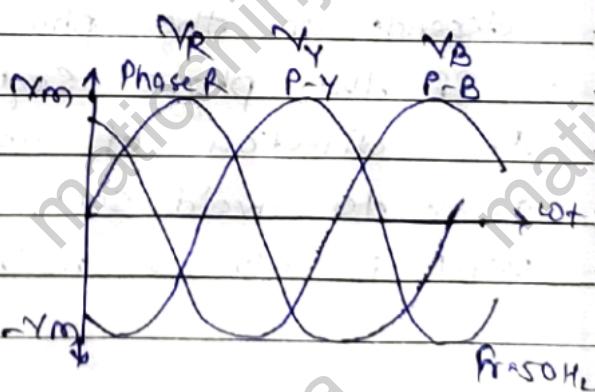
R, R', Y, Y', B, B' are the Armature windings displaced by 120°

• Construction :

- As shown in above fig. the armature winding is divided into three groups. The three coils are $R-R', Y-Y', B-B'$.

- All these coils are mounted on the same shaft & are physically placed at 120° from each other.

- When these coils rotate in the flux produced by the permanent magnet, emf is induced into these coils.



• Waveforms :

- These emf as shown in fig. are sinusoidal of equal amplitude & equal frequency but they are displaced by 120° from each other.

- V_R, V_Y & V_B are one 3-ph vfg. If V_{R12} is considered as reference then V_Y lags V_R by 120° & V_B lags V_Y by 120° .

fig. vfg induced in 3 coil.

* Comparison of 1-ph & 3-ph system

Parameter	1-ph System	3-ph System
① Voltage.	Low (230V)	High (415V)
② Transmission η	Low	High
③ Size of m/c to produce same O/P	Larger	Smaller
④ Cross sectional area of conductor	Larger	small
⑤ Application	Domestic, Small power application	Industrial, Large power application

* Phase Sequence :

• Definition - The phase sequence is defined as the sequence in which the three phases reach their maximum positive values. Normally the phase sequence is R-Y-B. The three phase colours used to denote 3 ph's are Red, Yellow & Blue.

• Importance of Phase Sequence :

- The direction of rotation of the three phases machine depends on the phase sequence.
- If the phase sequence is changed e.g. R-B-Y then the direction of rotation will be reversed. In order to avoid such things, the phase sequence of R-Y-B is always maintained.

* Types of Three Phase Connection :

1) Star Connection

2) Delta Connection

1) Star Connection (Wye Connection) :

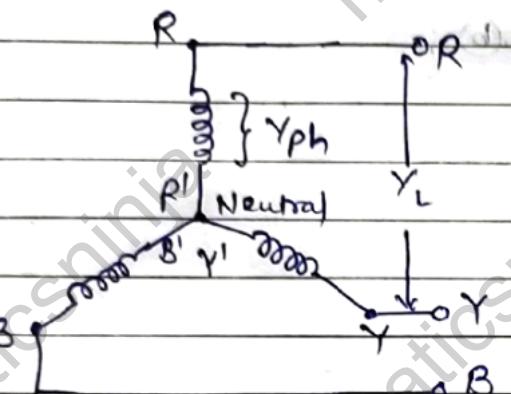


fig.(a) Star Connection

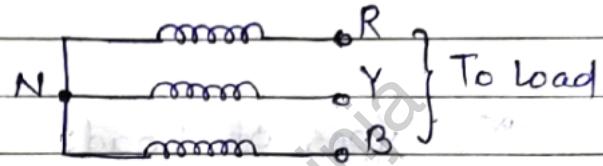


fig.(b) Equivalent circuit

- In above fig. Shows the Star or wye connection of the three alternator winding.
- This configuration is obtained by connecting one end of the three phase winding together.
- We can connect either R,Y,B or R',Y',B' together. This common point is called as the Neutral Point & it is denoted by N.
- The three remaining end of the winding are brought out for the external connection. These ends are denoted by R-Y-B as shown in fig.(b).

2) Delta Connection :

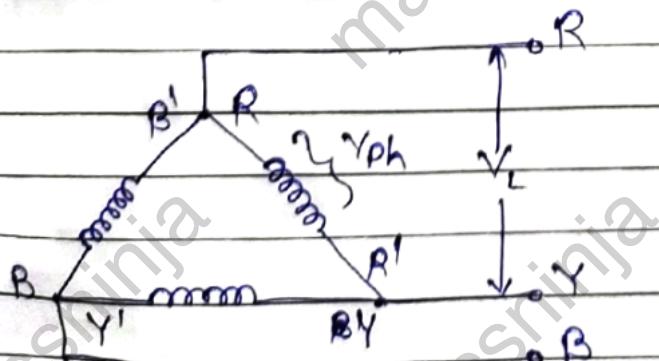


fig.(a) Delta or Mesh Connection

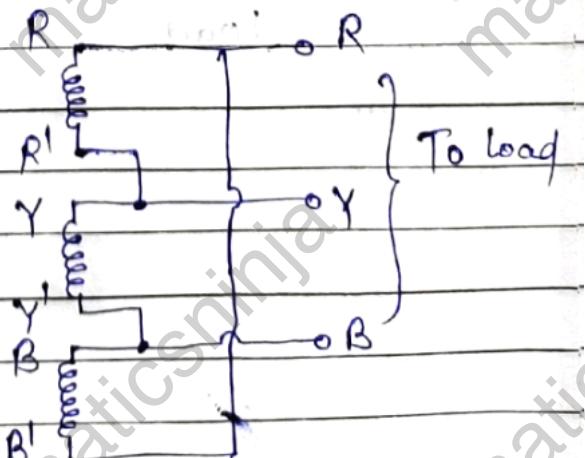


fig.(b) Equivalent circuit

- In above fig. Shows the delta connection or mesh conn. of the three alternator winding.
- In delta or mesh configuration is obtained by connection one end of winding to the starting end of the other winding such that it produces a closed loop as shown in fig.(b).

* Types of Loads :

- 1) Balanced Load
- 2) Unbalanced Load

⇒ Balanced Load :

- Defn : A balanced load is that in which magnitudes of all impedances connected in the load are equal & the phase angles of them also are equal it is called as balanced load.

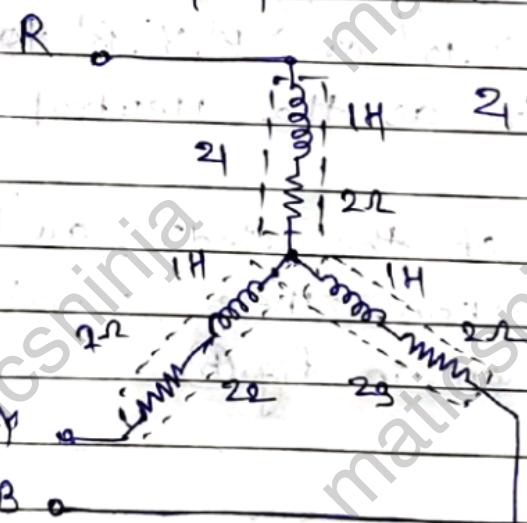


fig.(a) Balanced Star Connected Load.

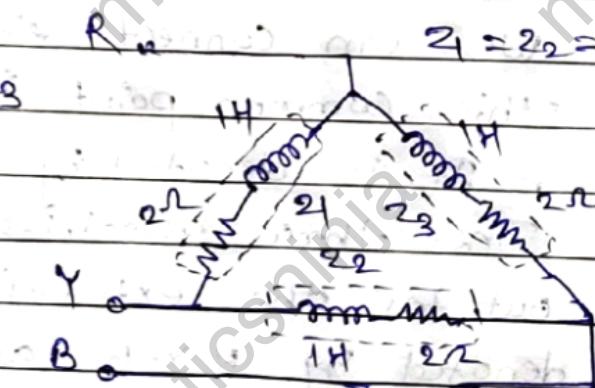


fig.(b) Balanced Delta Connected Load.

2) Unbalanced Load :

- Defn: If a load does not satisfy the condition of balanced, then its called as the Unbalanced load.
- If the magnitude & phase angle of the three impedances Z_1, Z_2 & Z_3 diff. from each other, then the load is said to be unbalanced.

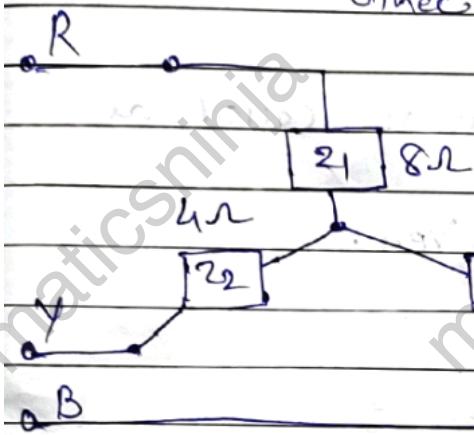


fig. (a) Unbalanced Star load

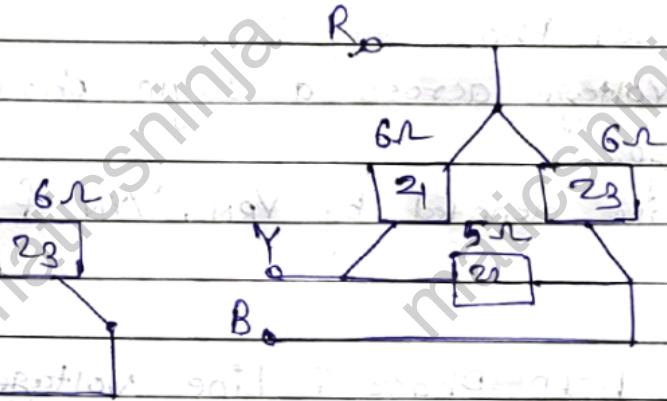


fig. (b) Unbalanced delta load

In fig. (b) $Z_1 = Z_3 = 6\Omega$ still this is an unbalanced delta connection because all the impedances are not equal.

* Three Phase Balanced Star Load :

- Line Voltage & Phase Voltage for star connected supply :

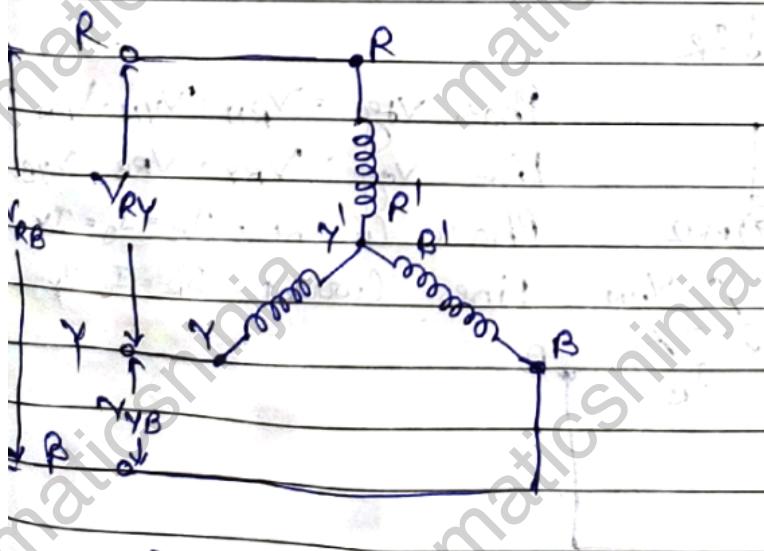


fig. (a) Line voltage

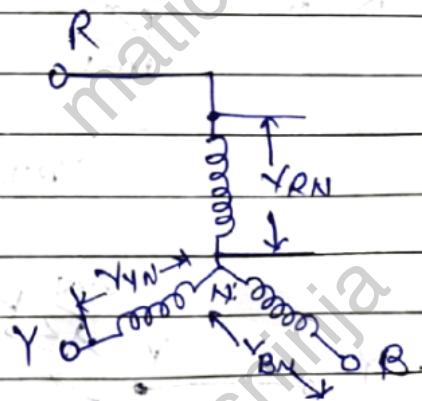


fig. (b) Phase voltage

- Definition of line V_{Lg} :
 - If R, Y & B are called as supply lines, then the potential difference b/w any two lines is known as the line V_{Lg} .
 - V_{RY} , V_{RB} , V_{BY} , V_{YR} , V_{BR} & V_{RY} are six possible line voltages.

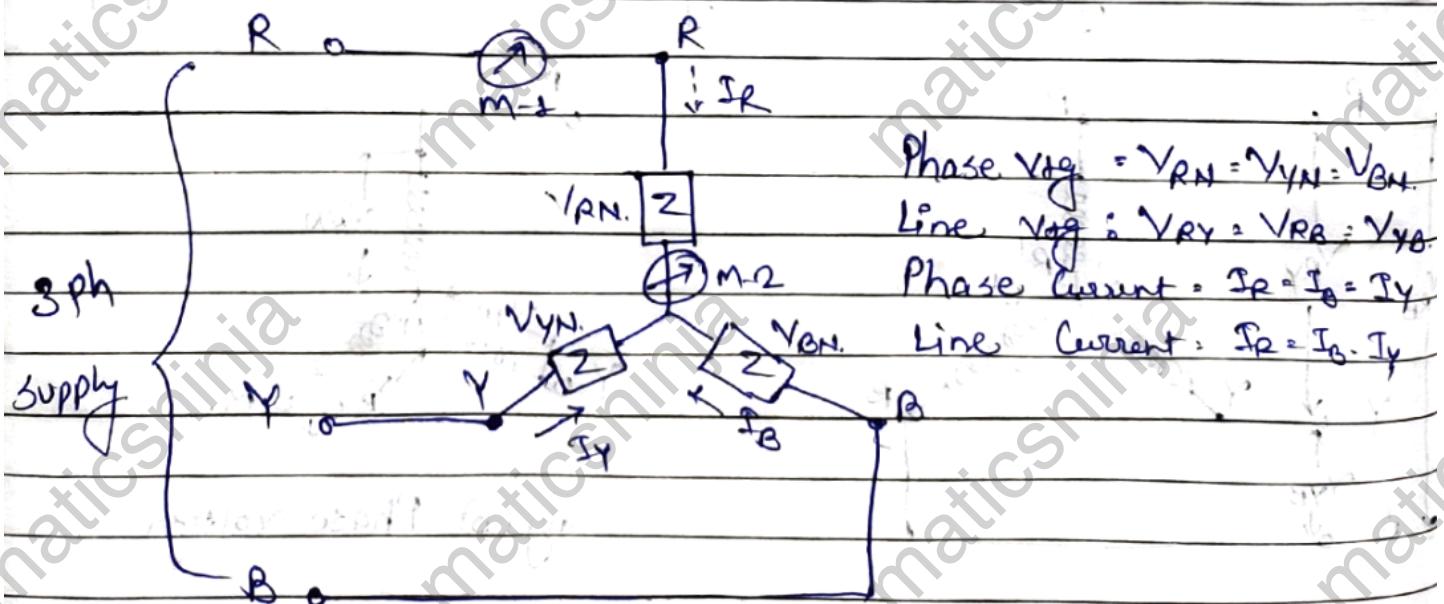
- Definition of Phase V_{ph} :
 - The voltage across a single phase is called as phase voltage.
 - They are denoted by V_{RN} , V_{YN} & V_{BN} .

* Relation b/w Phase & Line Voltage :

- For a star connected load, the magnitude of line V_{Lg} is $\sqrt{3}$ times higher than that of a phase V_{ph} .
- $\therefore V_L = \sqrt{3} V_{ph}$

* Relation b/w Phase & Line Current :

* Line & Phase Current for star connected Supply :



- Definition of Phase Current :

- The current passing through any branch of the star connected load is called as phase current.
- $I_R, I_Y \text{ & } I_B$ are the phase currents.
- Meter - 2 measures the phase current I_R .

- Definition of Line Current :

- The current passing through any line R, Y, B is called as line current.
- Meter - 1 measured the line current.
- It is denoted by I_L .

★ Relation b/w Phase & Line Current :

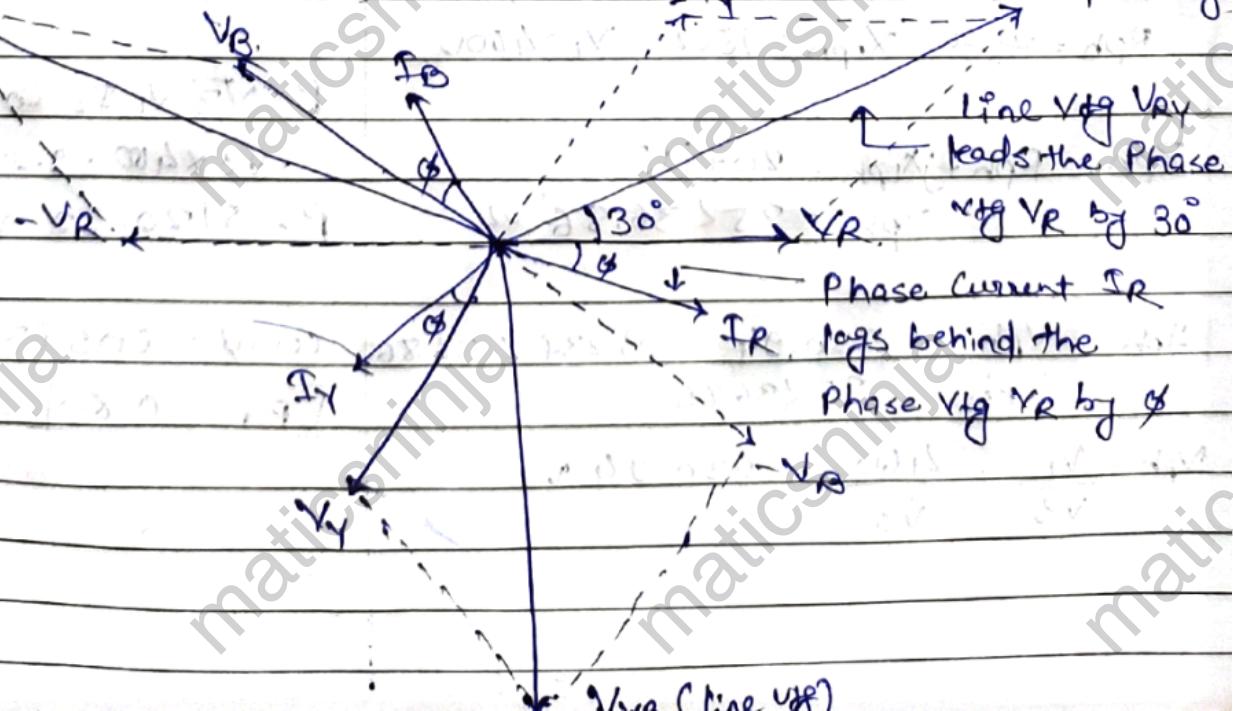
- As the current flowing through each branch line is equal to the current flowing through the corresponding branch, the line current is equal to the phase current.

$$\therefore I_L = I_{ph}$$

* The Complete Phasor diagram :

(Line voltage)

V_{YR}



Numerical on Star Load :

- ① A 3-ph Star Connected load has a resistance of 16Ω & an inductive reactance of 12Ω in each branch. It is supplied from 3 ph 400V, 50Hz supply. Calculate line & Phase current & Power input in Watt.

Soln: Given Data,

$$R_{ph} = 16\Omega, X_{Lph} = 12\Omega, f = 50\text{Hz}, V_L = 400\text{V}$$

$$\text{in star: } I_L = I_{ph}$$

$$I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{230.94}{20 + j36.86} = 11.547\angle -36.86^\circ \text{A}$$

$$V_{ph} = \frac{V_L}{\sqrt{3}} = \frac{400}{\sqrt{3}} = 230.94\text{V}$$

$$Z_{ph} = R_{ph} + jX_{ph} = 16 + j12 = 20 + j36.86$$

$$I_L = I_{ph} = 11.547\angle -36.86^\circ \text{A}$$

$$P = \sqrt{3} V_L I_L \cos \phi$$

$$P = \sqrt{3} \times 400 \times 11.547 \times \cos(-36.86)$$

$$P = 6400.82 \text{Watt} \quad \dots \text{Ans}$$

- ② Three coil each having a resistance of 20Ω & reactance of 15Ω are connected in star to a 400V, 3ph, 50Hz supply. Calculate: (1) Line current (2) Power supplied (3) Power factor.

Soln: Given Data,

$$R_{ph} = 20\Omega, X_{Lph} = 15\Omega, V_L = 400\text{V}$$

$$Z_{ph} = R_{ph} + jX_{ph} = 20 + j15$$

$$Z_{ph} = 25 + j36.86 \Omega$$

$$P = \sqrt{3} V_L I_L \cos \phi$$

$$= \sqrt{3} \times 400 \times 9.237 \times \cos(36.86)$$

$$P = 5120.32 \text{Watt}$$

$$I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{230.94}{25 + j36.86} = 9.237 \angle -36.86^\circ$$

$$\cos \phi = \cos(36.86)$$

$$|P.F| = 0.80$$

$$V_{ph} = \frac{V_L}{\sqrt{3}} = \frac{400}{\sqrt{3}} = 230.94\text{V}$$

③ Three coil each with a resistance of 10Ω & inductance of 0.35 mH are connected in star to a 3 ph - 400V, 50Hz supply. Calculate line current & total power consumed.

Soln: Given Data, star load.

$$R_{ph} = 10\Omega, L = 0.35 \text{ mH}, V_L = 400V, f = 50 \text{ Hz}$$

find: I_{ph} & P

$$X_{ph} = 2\pi f L_{ph} = 2 \times 3.14 \times 50 \times 0.35 \times 10^3 \Omega$$

$$Z_{ph} = \sqrt{(R)^2 + (X_{ph})^2} = \sqrt{(10)^2 + (109.9)^2} = 110.35 \angle 84.8^\circ$$

$$V_{ph} = \frac{V_L}{\sqrt{3}} = \frac{400}{\sqrt{3}} = 230.94 \text{ V}$$

$$\therefore I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{230.94}{110.35 \angle 84.8^\circ} = 2.09 \angle -84.8^\circ \text{ A}$$

$$P = \sqrt{3} V_L I_L \cos \phi$$

$$= \sqrt{3} \times 400 \times 2.09 \times \cos(84.8)$$

$$P = 131.23 \text{ Watt}$$

* Three Phase Balanced Delta Load :

- Line V_{fg} & Phase V_{tg} for Delta Connected Supply :

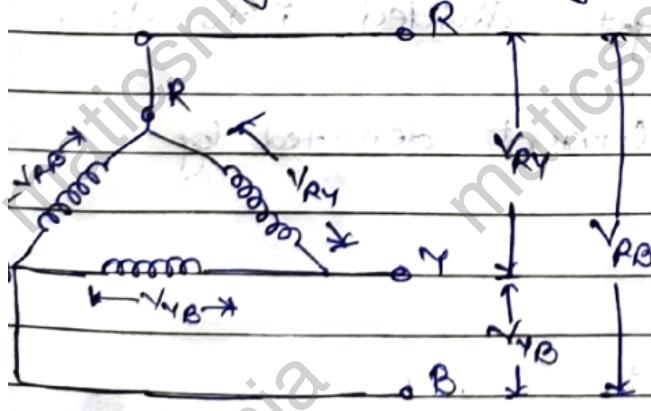


fig. Delta Connection

• Line V_{fg} : The line V_{fg} is defined as the potential diff. betw two line. So V_{RY} , V_{YA} & V_{BY} are the line V_{fg} .

• Phase V_{tg} : The V_{tg} measured across a single winding is called as the wt phase V_{tg} . Note that V_{RY} , V_{YA} & V_{BY} which

are same as line V_{fg} . Thus for delta connected supply, the phase V_{tg} are same as line V_{fg} .

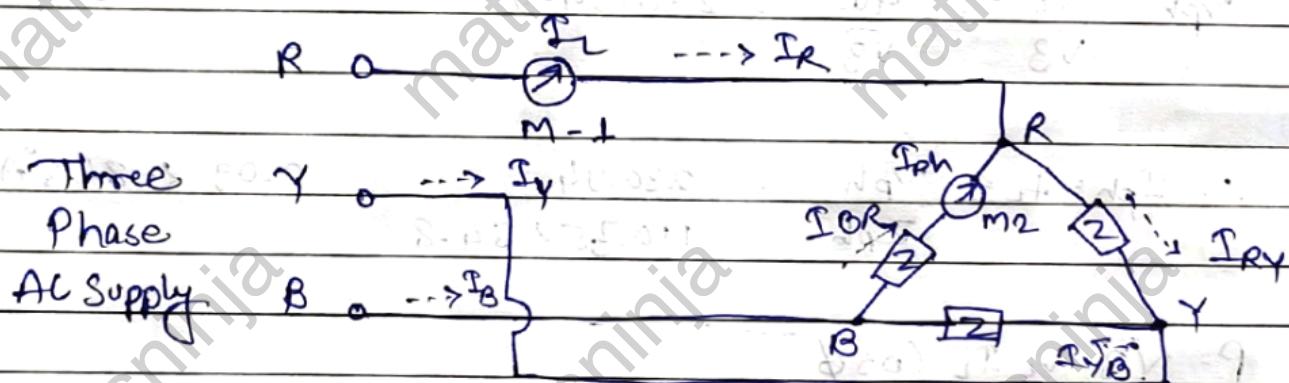
* Relation betn Phase & Line V_{TG}:

- for delta connected supply the phase V_{Tg} , V_{YB} & V_{RB} are same and line voltage $\sqrt{3}V_L$, V_{YB} & V_{RB} .

$$\therefore V_{ph} = V_L = V_{AY}, V_{RB}, V_{YB}$$

$$\therefore [V_{ph} = V_L]$$

* Line & Phase Current for Delta Connection:



Phase Currents I_{RY} , I_{YA} , I_{RB}
Line Currents I_R , I_Y , I_B

• Line Current is denoted by I_R , I_Y & I_B

• ~~Phase Current~~: - The line current is higher than the phase current. This is because at node R, the line current I_R gets divided into two phase current I_{RY} & I_{RB} .

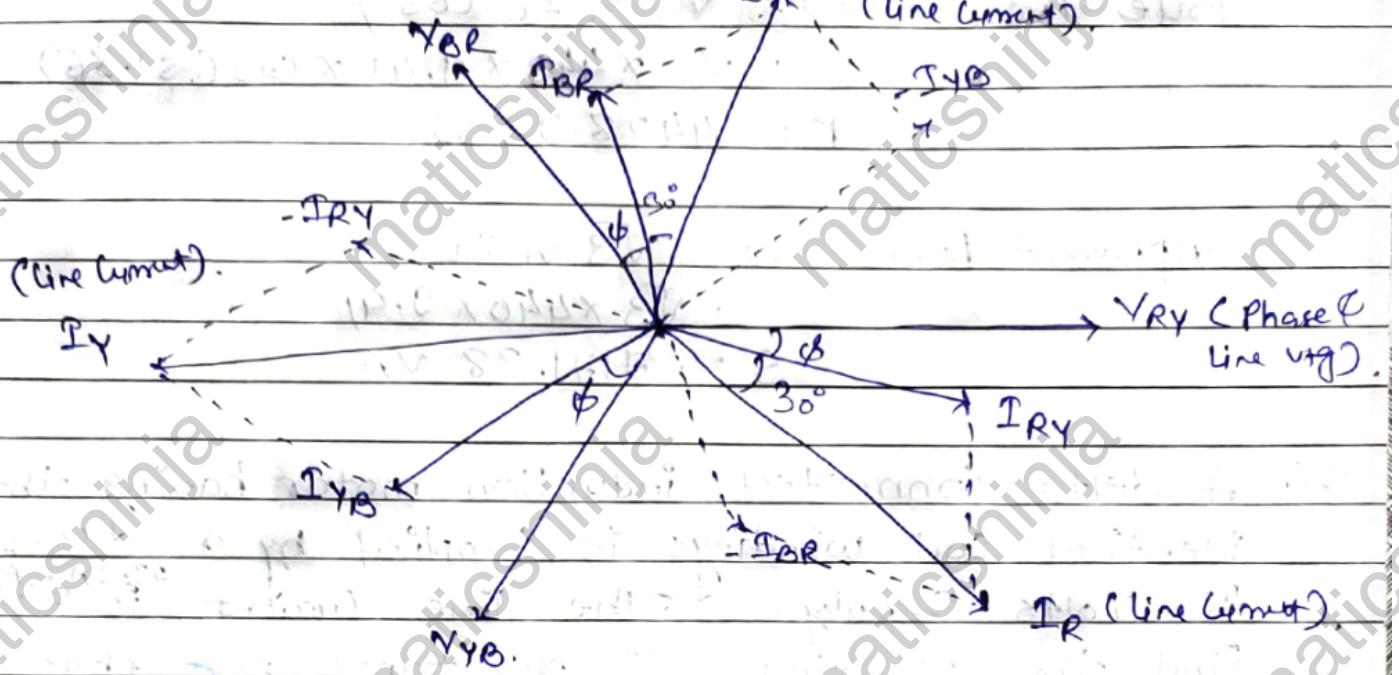
- So that the phase current denoted by I_{RY} , I_{RB} , & I_{YA} .

* Relation betn I_R & I_{ph} :

- The relation betn line current & Phase current for a delta connected balanced load is as follow :-

$$I_R = \sqrt{3} I_{ph}$$

* The Complete Phasor diagram for Delta Load:



* Numerical on Delta Connected Load (Balanced) :

- ① A three-phase delta connected balanced load having a resistance of $50\ \Omega$ / Phase & capacitance of $50\ \mu F$ / Phase, is supplied by $440V$, 3ϕ , 50Hz AC Supply. Determine : ① Line Current
 ② Phase Current ③ True Power ④ Apparent P/W.

Soln: Given Data ,

$$R = 50\ \Omega/\text{ph}, C = 50\ \mu F/\text{Phase}, V_1 = V_{ph} = 440V, \\ 3\phi, f = 50\text{Hz}.$$

$$I_L = \sqrt{3} I_{ph} = \sqrt{3} \times \frac{440}{50} = 8\cancel{.}5 A$$

$$I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{440}{80.97} = 5.43\ A$$

$$Z_{ph} = \sqrt{R^2 + X_C^2} = \sqrt{(50)^2 + (63.69)^2} = 80.97 \angle 51.86^\circ \Omega$$

$$X_C = \frac{1}{2\pi f C} = \frac{1}{2 \times 3.14 \times 50 \times 50 \times 10^{-6}} = 63.69\ \Omega$$

$$\text{True Power (P)} = \sqrt{3} V_L I_L \cos \phi$$

$$= \sqrt{3} \times 440 \times 3.41 \times \cos(36.86)$$

$$P = 4428.93 \text{ W}$$

$$\text{Apparent Power (S)} = \sqrt{3} V_L I_L$$

$$= \sqrt{3} \times 440 \times 3.41$$

$$S = 7171.38 \text{ VA}$$

- ② A delta connected induction motor having three identical coil windings is supplied by a 3-ph 400 Volts supply. The line current is 43.3 A & Power is 24 kW. Find the resistance & reactance per phase of the winding.

Given Data,

$$I_L = 43.3 \text{ A}, P = 24 \text{ kW}, V_L = 400 \text{ V}$$

for delta connection, $V_L = V_{ph} = 400 \text{ V}$.

$$I_{ph} = \frac{I_L}{\sqrt{3}} = \frac{43.3}{\sqrt{3}} = 25 \text{ A}$$

$$Z_{ph} = \frac{V_{ph}}{I_{ph}} = \frac{400}{25} = 16 \Omega$$

$$P = \sqrt{3} V_L I_L \cos \phi$$

$$24 \times 10^3 = \sqrt{3} \times 400 \times 43.3 \times \cos \phi$$

$$\cos \phi = \frac{24 \times 10^3}{\sqrt{3} \times 400 \times 43.3} = 0.8$$

$$\cos \phi = \frac{R_{ph}}{Z_{ph}}$$

$$R_{ph} = Z_{ph} \cos \phi = 16 \times 0.8 = 12.8 \Omega$$

$$\sin \phi = \frac{X_{ph}}{Z_{ph}}$$

$$X_{ph} = Z_{ph} \sin \phi = 16 \times \sin(36.86) = 9.59 \Omega$$

③ A delta connected load having phase impedance of $(8+j6)\Omega$ supplied by a star connected alternator, having line voltage of 230V. Determine :
 ① Phase Current ② Line Current ③ Power factor ④ R.P%

Soln : Given Data,

$$Z_{ph} = (8+j6)\Omega, V_L = V_{ph} = 230V$$

$$Z_{ph} = \sqrt{R^2 + X^2} = \sqrt{8^2 + 6^2} = 10\Omega$$

$$P.f = \cos\phi = \frac{R}{Z_{ph}} = \frac{8}{10} = 0.8$$

$$\sin\phi = \frac{X}{Z_{ph}} = \frac{6}{10} = 0.6$$

$$I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{230}{10} = 23A$$

$$I_L = \sqrt{3} I_{ph} = \sqrt{3} \times 23 = 39.83A$$

$$\begin{aligned} \text{Reactive Power } (Q) &= \sqrt{3} V_L I_L \sin\phi \\ &= \sqrt{3} \times 230 \times 39.83 \times 0.6 \\ &= 9522 \text{ VA} = 9.522 \text{ kVA} \end{aligned}$$

④ A three phase system supplied a load of 30kW at a P.F of 0.8. The line voltage is 250V. If the load is connected in ① star ② delta. Then calculate line current & phase current.

Soln : Given Data,

$$P = 30 \text{ kW}, P.f = \cos\phi = 0.8, V_L = 250V$$

• for star connected load :

$$V_{ph} = \frac{V_L}{\sqrt{3}} = \frac{250}{\sqrt{3}} = 144.33V$$

$$P = \sqrt{3} V_L I_L \cos\phi$$

$$I_L = \frac{30 \times 10^3}{\sqrt{3} \times V_L (250) \times 0.8} = 86.6A$$

$$I_L = I_{ph} = 86.6A$$

$$Z_{ph} = \frac{V_{ph}}{I_{ph}} = \frac{144.33}{86.6} = 1.66 \Omega$$

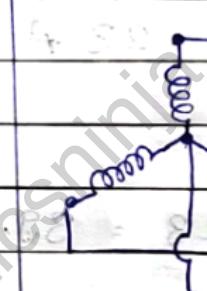
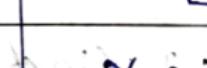
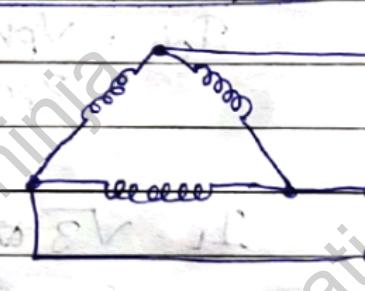
• For Delta Connected Load:

$$Y_L = Y_{ph} = 250 \text{ S}$$

$$I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{250}{1.66} = 150.6 \text{ A}$$

$$I_L = \sqrt{3} I_{ph} = \sqrt{3} \times 150.6 = 260.84 \text{ A}$$

* Comparison of Star & Delta Connection:

Sr. No.	Parameter	Star Connection	Delta Connection
①	Way of Connection	 OR 	
②	Voltage Relationship	$Y_L = \sqrt{3} Y_{ph}$	$Y_L = Y_{ph}$
③	Current Relationship	$I_L = I_{ph}$ $I_{ph} = Y_{ph}/Z_{ph}$	$I_L = \sqrt{3} I_{ph}$
④	Neutral wire.	Can be Connected	Not necessary

Advantages

Subject I/C

Mr. Bhosiwale, G.H